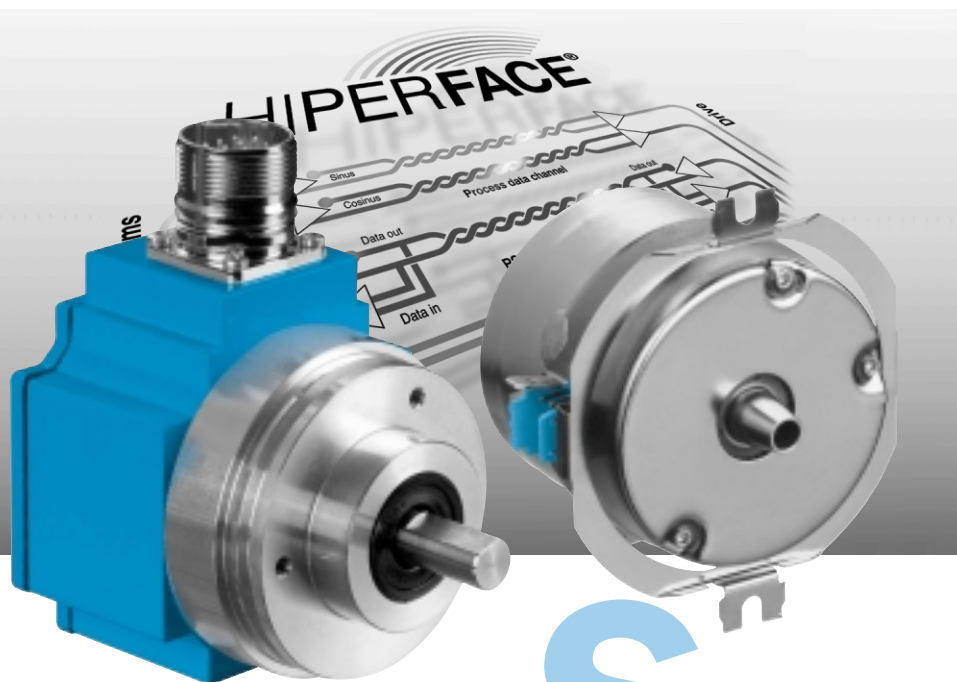


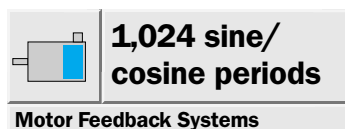
SinCos® SRS 50, SRM 50, SRS 60, SRM 60 SRS 50 Standalone, SRM 50 Standalone: Motor Feedback Systems with HIPERFACE® - Interface for Servo Motors



Select the motor feedback system to suit your individual requirements.

Possible product variations:

- Plug-in shaft or tapered shaft with different stator supports
- 6 mm or 10 mm shaft with connector or cable exit
- Versions for integration, attachment, or standalone versions

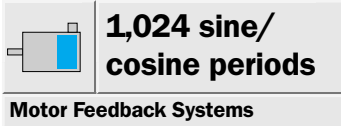


SRS/SRM series of motor feedback systems are used worldwide in many different applications and environments.

Absolute positioning with 32,768 steps per revolution and a maximum of 4,096 revolutions give a total resolution of 134,217,28 steps.

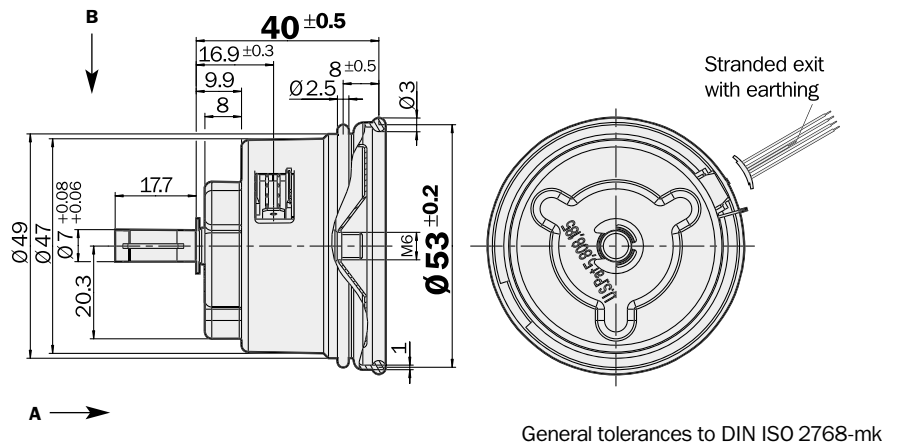
Writing motor-specific data to the electronic type label and programming are important features of these series.

SICK | STEGMANN

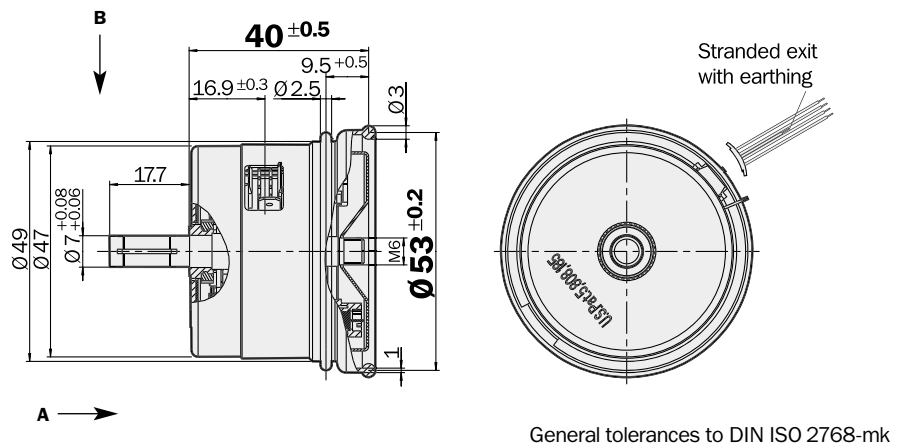


- 1,024 sine/cosine periods per revolution
- Absolute position with a resolution of 32,768 steps per revolution
- 4,096 revolutions can be measured (Multiturn)
- Programming of the positional value
- Electronic type label

Dimensional drawing SRS 50, rubber support Ø 50



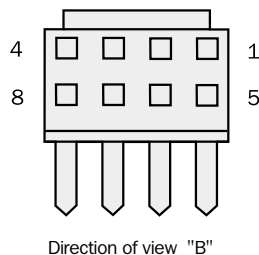
Dimensional drawing SRM 50, rubber support Ø 50



PIN and wire allocation

PIN	Signal	Colour of Wires	Explanation
1	U _s	red	Supply voltage 7 ... 12 V
2	GND	blue	Ground connection
3	REFSIN	brown	Process data channel
4	REFCOS	black	Process data channel
5	Data +	grey	RS-485-parameter channel
6	Data -	green	RS-485-parameter channel
7	+ SIN	white	Process data channel
8	+ COS	pink	Process data channel

Caution: To ensure proper function, the screen connection strand (200 mm) MUST be connected. It is included in the supply.



Accessories

- Connection technology
- Fixing technology
- Programming tool

Technical Data		Plug-in Shaft SRS/SRM 50	SRS	SRM									
Number of sine/cosine periods per revolution	1,024												
Dimensions	mm (see dimensional drawing)												
Mass	0.2 kg												
Inertial rotor moment	10 gcm ²												
Type of code for the absolute value	Binary												
Code sequence for clockwise shaft rotation, looking in direction "A" (see dimensional drawing)	Increasing												
Measurement step after generating arctan with 12 bit resolution	0.3 angular seconds												
Total number of steps	Single SRS 32,768												
	Multi SRM 134,217,728 = 32,768 x 4,096												
Error limits for the digital absolute value													
via RS 485	± 90 angular seconds												
Error limits for evaluating the "1,024" signals, integral non-linearity		± 45 angular seconds											
Non-linearity within a sine/cosine period													
differential non-linearity	± 7 angular seconds												
Output frequency for sine/cosine signals	0 ... 200 kHz												
Working speed up to which the absolute position can be reliably produced		6,000 min ⁻¹											
Max. operating speed	12,000 min ⁻¹												
Max. angular acceleration	0.2 x 10 ⁶ rad/s ²												
Operating torque	0.2 Ncm												
Starting torque	0.4 Ncm												
Permissible shaft movement													
static	radial/axial	± 0.5 mm/± 0.75 mm											
dynamic	radial/axial	± 0.1 mm/± 0.2 mm											
Angular motion, perpendicular to the rotational axis													
static		± 0.005 mm/mm											
dynamic		± 0.0025 mm/mm											
Life of ball bearings		3.6 x 10 ⁹ rotations											
Working temperature range		- 20 ... + 115 °C											
Storage temperature range		- 40 ... + 125 °C											
Permissible relative humidity ¹⁾		90 %											
Resistance													
to shocks ²⁾		100/10 g/ms											
to vibration ³⁾		20/10 ... 2000 g/Hz											
Protection to IEC 60529 ⁴⁾		IP 40											
EMC ⁵⁾													
Operating voltage range		7 ... 12 V											
Recommended supply voltage		8 V											
Max. operating current, no load		80 mA											
Available memory area													
within EEPROM 512		128 bytes											
within EEPROM 2048		1,792 bytes											
Interface signals													
Process data channel = SIN, REFSIN, COS, REFCOS	Analogue, differential												
Parameter channel = RS 485	Digital												

¹⁾ Condensation not permissible

²⁾ To DIN EN 60068-2-27

³⁾ To DIN EN 60068-2-6

⁴⁾ With mating connector inserted

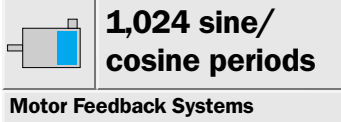
⁵⁾ To DIN EN 61000-6-2 and DIN 61000-6-3

The EMC according to the standards quoted is achieved when the motor feedback system is mounted in an electrically conductive housing, which is connected to the central earthing point of the motor controller via a cable screen. This is also where the GND (0 V) connection of the supply voltage is linked to earth. Users must perform their own tests when other screen designs are used.

Ordering information

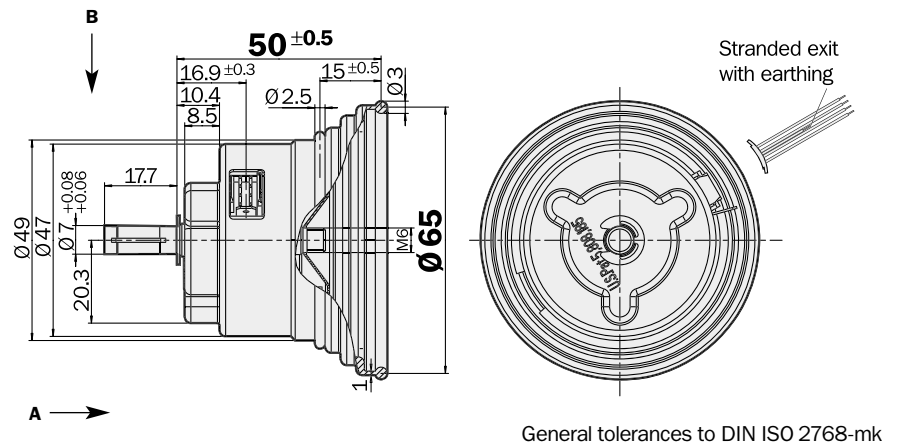
SRS/SRM 50; plug-in shaft Ø 7mm; rubber support

Type	Part no.	Description
SRS50-HAA0-K01	1 034 170	Single, 512 EEprom, connector
SRS50-HAV0-K01	1 034 174	Single, 512 EEprom, stranded cable
SRS50-HAA0-K02	1 034 171	Single, 2048 EEprom, connector
SRS50-HAV0-K02	1 034 175	Single, 2048 EEprom, stranded cable
SRM50-HAA0-K01	1 034 104	Multi, 512 EEprom, connector
SRM50-HAV0-K01	1 034 109	Multi, 512 EEprom, stranded cable
SRM50-HAA0-K02	1 034 105	Multi, 2048 EEprom, connector
SRM50-HAV0-K02	1 034 110	Multi, 2048 EEprom, stranded cable

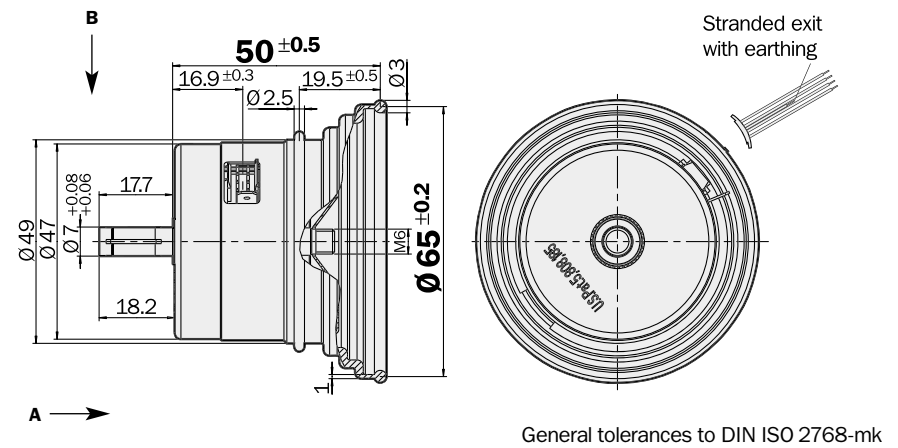


- 1,024 sine/cosine periods per revolution
- Absolute position with a resolution of 32,768 steps per revolution
- 4,096 revolutions can be measured (Multiturn)
- Programming of the positional value
- Electronic type label

Dimensional drawing SRS 60, rubber support Ø 60



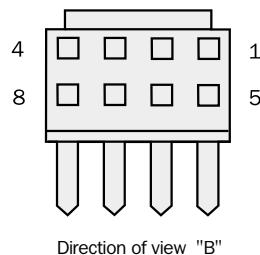
Dimensional drawing SRM 60, rubber support Ø 60



PIN and wire allocation

PIN	Signal	Colour of Wires	Explanation
1	U _s	red	Supply voltage 7 ... 12 V
2	GND	blue	Ground connection
3	REFSIN	brown	Process data channel
4	REFCOS	black	Process data channel
5	Data +	grey	RS-485-parameter channel
6	Data -	green	RS-485-parameter channel
7	+ SIN	white	Process data channel
8	+ COS	pink	Process data channel

Caution: To ensure proper function, the screen connection strand (200 mm) MUST be connected. It is included in the supply.



Accessories

- Connection technology
- Fixing technology
- Programming tool

Technical Data		Plug-in Shaft SRS/SRM 60	SRS	SRM									
Number of sine/cosine periods per revolution	1,024												
Dimensions	mm (see dimensional drawing)												
Mass	0.2 kg												
Inertial rotor moment	10 gcm ²												
Type of code for the absolute value	Binary												
Code sequence for clockwise shaft rotation, looking in direction "A" (see dimensional drawing)	Increasing												
Measurement step after generating arctan with 12 bit resolution	0.3 angular seconds												
Total number of steps	Single SRS 32,768												
	Multi SRM 134,217,728 = 32,768 x 4,096												
Error limits for the digital absolute value													
via RS 485	± 90 angular seconds												
Error limits for evaluating the "1,024" signals, integral non-linearity		± 45 angular seconds											
Non-linearity within a sine/cosine period													
differential non-linearity	± 7 angular seconds												
Output frequency for sine/cosine signals	0 ... 200 kHz												
Working speed up to which the absolute position can be reliably produced		6,000 min ⁻¹											
Max. operating speed	12,000 min ⁻¹												
Max. angular acceleration	0.2 x 10 ⁶ rad/s ²												
Operating torque	0.2 Ncm												
Starting torque	0.4 Ncm												
Permissible shaft movement													
static	radial/axial	± 0.5 mm/± 0.75 mm											
dynamic	radial/axial	± 0.1 mm/± 0.2 mm											
Angular motion, perpendicular to the rotational axis													
static		± 0.005 mm/mm											
dynamic		± 0.0025 mm/mm											
Life of ball bearings		3.6 x 10 ⁹ rotations											
Working temperature range		- 20 ... + 115 °C											
Storage temperature range		- 40 ... + 125 °C											
Permissible relative humidity ¹⁾		90 %											
Resistance													
to shocks ²⁾		100/10 g/ms											
to vibration ³⁾		20/10 ... 2000 g/Hz											
Protection to IEC 60529 ⁴⁾		IP 40											
EMC ⁵⁾													
Operating voltage range		7 ... 12 V											
Recommended supply voltage		8 V											
Max. operating current, no load		80 mA											
Available memory area													
within EEPROM 512		128 bytes											
within EEPROM 2048		1,792 bytes											
Interface signals													
Process data channel = SIN, REFSIN, COS, REFCOS	Analogue, differential												
Parameter channel = RS 485	Digital												

¹⁾ Condensation not permissible

²⁾ To DIN EN 60068-2-27

³⁾ To DIN EN 60068-2-6

⁴⁾ With mating connector inserted

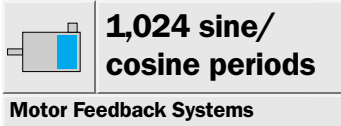
⁵⁾ To DIN EN 61000-6-2 and DIN 61000-6-3

The EMC according to the standards quoted is achieved when the motor feedback system is mounted in an electrically conductive housing, which is connected to the central earthing point of the motor controller via a cable screen. This is also where the GND (0 V) connection of the supply voltage is linked to earth. Users must perform their own tests when other screen designs are used.

Ordering information

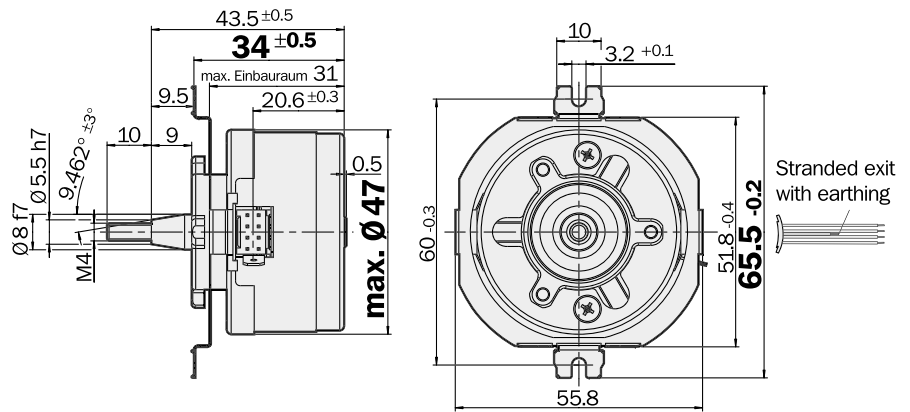
SRS/SRM 60; plug-in shaft Ø 7mm; rubber support

Type	Part no.	Description
SRS60-HAA0-K01	1 034 213	Single, 512 EEprom, connector
SRS60-HAV0-K01	1 034 215	Single, 512 EEprom, stranded cable
SRS60-HAA0-K02	1 034 214	Single, 2048 EEprom, connector
SRS60-HAV0-K02	1 034 216	Single, 2048 EEprom, stranded cable
SRM60-HAA0-K01	1 034 153	Multi, 512 EEprom, connector
SRM60-HAV0-K01	1 034 155	Multi, 512 EEprom, stranded cable
SRM60-HAA0-K02	1 034 154	Multi, 2048 EEprom, connector
SRM60-HAV0-K02	1 034 156	Multi, 2048 EEprom, stranded cable



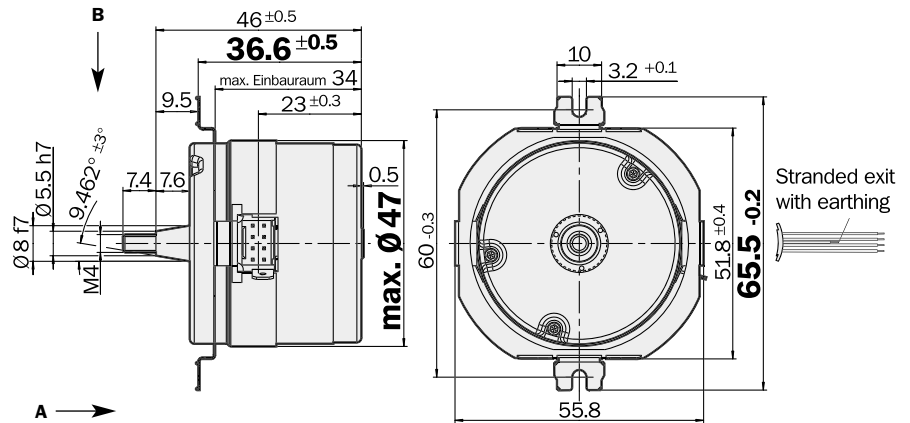
- 1,024 sine/cosine periods per revolution
- Absolute position with a resolution of 32,768 steps per revolution
- 4,096 revolutions can be measured (Multiturn)
- Programming of the positional value
- Electronic type label

Dimensional drawing SRS 50, spring mounting plate Ø 66



General tolerances to DIN ISO 2768-mk

Dimensional drawing SRM 50, spring mounting plate Ø 66

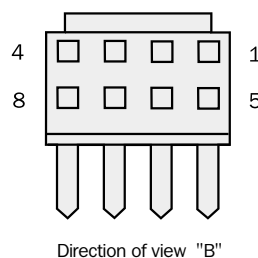


General tolerances to DIN ISO 2768-mk

PIN and wire allocation

PIN	Signal	Colour of Wires	Explanation
1	U _s	red	Supply voltage 7 ... 12 V
2	GND	blue	Ground connection
3	REFSIN	brown	Process data channel
4	REFCOS	black	Process data channel
5	Data +	grey	RS-485-parameter channel
6	Data -	green	RS-485-parameter channel
7	+ SIN	white	Process data channel
8	+ COS	pink	Process data channel

Caution: To ensure proper function, the screen connection strand (200 mm) MUST be connected. It is included in the supply.



Screening:

The encoder housing for the integrated encoder is connected to the motor, via the torque support. The connection space is thus screened via the motor housing such that, within the connection space, unscreened connection strands can be used.

U_s and GND are internally connected to the housing, through 2.2 nF capacitors.

Accessories

- Connection technology
- Fixing technology
- Programming tool

Technical Data		Tapered Shaft SRS/SRM 50	SRS	SRM									
Number of sine/cosine periods per revolution	1,024												
Dimensions	mm (see dimensional drawing)												
Mass	0.2 kg												
Inertial rotor moment	10 gcm ²												
Type of code for the absolute value	Binary												
Code sequence for clockwise shaft rotation, looking in direction "A" (see dimensional drawing)	Increasing												
Measurement step after generating arctan with 12 bit resolution	0.3 angular seconds												
Total number of steps	Single SRS 32,768												
	Multi SRM 134,217,728 = 32,768 x 4,096												
Error limits for the digital absolute value													
via RS 485	± 90 angular seconds												
Error limits for evaluating the "1,024" signals, integral non-linearity		± 45 angular seconds											
Non-linearity within a sine/cosine period													
differential non-linearity	± 7 angular seconds												
Output frequency for sine/cosine signals	0 ... 200 kHz												
Working speed up to which the absolute position can be reliably produced		6,000 min ⁻¹											
Max. operating speed	12,000 min ⁻¹												
Max. angular acceleration	0.2 x 10 ⁶ rad/s ²												
Operating torque	0.2 Ncm												
Starting torque	0.4 Ncm												
Permissible shaft movement													
static	radial/axial	± 0.5 mm/± 0.75 mm											
dynamic	radial/axial	± 0.1 mm/± 0.2 mm											
Angular motion, perpendicular to the rotational axis													
static		± 0.005 mm/mm											
dynamic		± 0.0025 mm/mm											
Life of ball bearings		3.6 x 10 ⁹ rotations											
Working temperature range		- 20 ... + 115 °C											
Storage temperature range		- 40 ... + 125 °C											
Permissible relative humidity ¹⁾		90 %											
Resistance													
to shocks ²⁾		100/10 g/ms											
to vibration ³⁾		20/10 ... 2000 g/Hz											
Protection to IEC 60529 ⁴⁾		IP 40											
EMC ⁵⁾													
Operating voltage range		7 ... 12 V											
Recommended supply voltage		8 V											
Max. operating current, no load		80 mA											
Available memory area													
within EEPROM 512		128 bytes											
within EEPROM 2048		1,792 bytes											
Interface signals													
Process data channel = SIN, REFSIN, COS, REFCOS	Analogue, differential												
Parameter channel = RS 485	Digital												

¹⁾ Condensation not permissible

²⁾ To DIN EN 60068-2-27

³⁾ To DIN EN 60068-2-6

⁴⁾ With mating connector inserted

⁵⁾ To DIN EN 61000-6-2 and DIN 61000-6-3

The EMC according to the standards quoted is achieved when the motor feedback system is mounted in an electrically conductive housing, which is connected to the central earthing point of the motor controller via a cable screen. This is also where the GND (0 V) connection of the supply voltage is linked to earth. Users must perform their own tests when other screen designs are used.

Ordering information

SRS/SRM 50; tapered shaft; spring mounting plate

Type	Part no.	Description
SRS50-HFA0-K01	1 034 222	Single, 512 EEprom, connector
SRS50-HFV0-K01	1 034 185	Single, 512 EEprom, stranded cable
SRS50-HFA0-K02	1 034 182	Single, 2048 EEprom, connector
SRS50-HFV0-K02	1 034 186	Single, 2048 EEprom, stranded cable
SRM50-HFA0-K01	1 034 118	Multi, 512 EEprom, connector
SRM50-HFV0-K01	1 034 122	Multi, 512 EEprom, stranded cable
SRM50-HFA0-K02	1 034 119	Multi, 2048 EEprom, connector
SRM50-HFV0-K02	1 034 123	Multi, 2048 EEprom, stranded cable

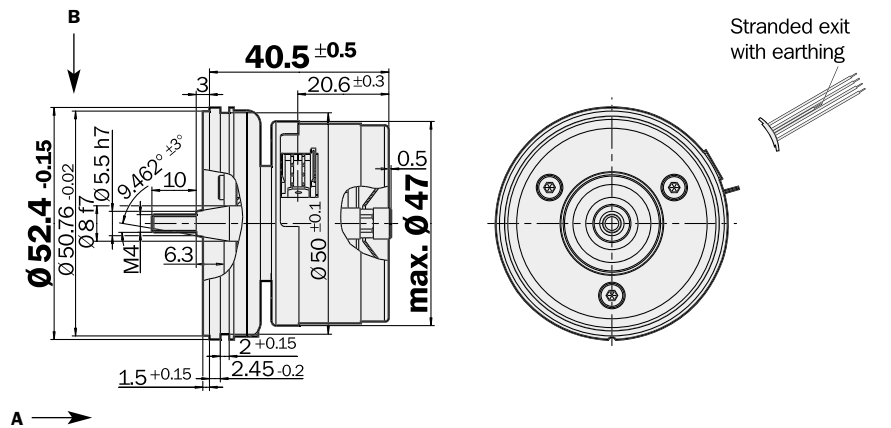


**1,024 sine/
cosine periods**

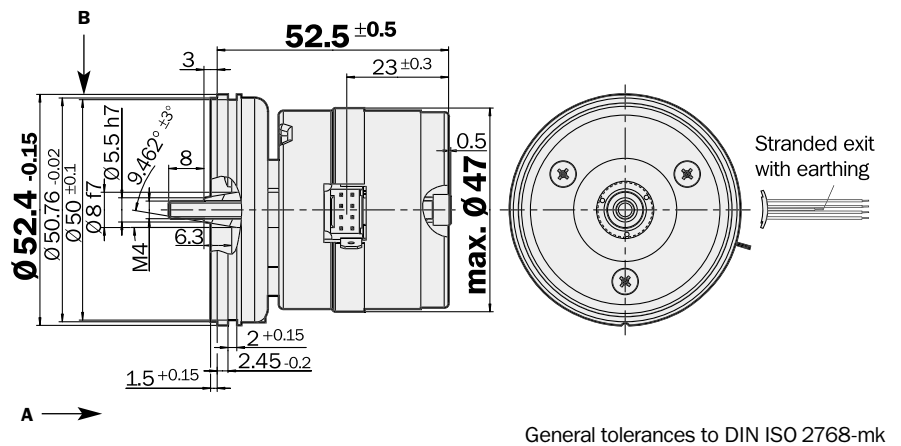
Motor Feedback Systems

- 1,024 sine/cosine periods per revolution
- Absolute position with a resolution of 32,768 steps per revolution
- 4,096 revolutions can be measured (Multiturn)
- Programming of the positional value
- Electronic type label

Dimensional drawing SRS 50, resolver support Ø 52



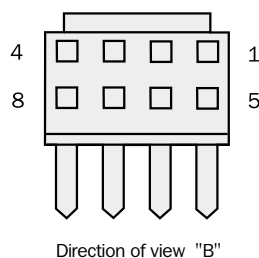
Dimensional drawing SRM 50, resolver support Ø 52



PIN and wire allocation

PIN	Signal	Colour of Wires	Explanation
1	U_s	red	Supply voltage 7 ... 12 V
2	GND	blue	Ground connection
3	REFSIN	brown	Process data channel
4	REFCOS	black	Process data channel
5	Data +	grey	RS-485-parameter channel
6	Data -	green	RS-485-parameter channel
7	+ SIN	white	Process data channel
8	+ COS	pink	Process data channel

Caution: To ensure proper function, the screen connection strand (200 mm) MUST be connected. It is included in the supply.



Accessories

- Connection technology
- Fixing technology
- Programming tool

Technical Data		Tapered Shaft SRS/SRM 50	SRS	SRM									
Number of sine/cosine periods per revolution		1,024											
Dimensions		mm (see dimensional drawing)											
Mass		0.2 kg											
Inertial rotor moment		10 gcm ²											
Type of code for the absolute value		Binary											
Code sequence for clockwise shaft rotation, looking in direction "A" (see dimensional drawing)		Increasing											
Measurement step after generating arctan with 12 bit resolution		0.3 angular seconds											
Total number of steps	Single SRS	32,768											
	Multi SRM	134,217,728 = 32,768 x 4,096											
Error limits for the digital absolute value													
via RS 485		± 90 angular seconds											
Error limits for evaluating the "1,024" signals,													
integral non-linearity		± 45 angular seconds											
Non-linearity within a sine/cosine period													
differential non-linearity		± 7 angular seconds											
Output frequency for sine/cosine signals		0 ... 200 kHz											
Working speed up to which the absolute position can be reliably produced		6,000 min ⁻¹											
Max. operating speed		12,000 min ⁻¹											
Max. angular acceleration		0.2 x 10 ⁶ rad/s ²											
Operating torque		0.2 Ncm											
Starting torque		0.4 Ncm											
Permissible shaft movement													
static	radial/axial	± 0.5 mm/± 0.75 mm											
dynamic	radial/axial	± 0.1 mm/± 0.2 mm											
Angular motion, perpendicular to the rotational axis													
static		± 0.005 mm/mm											
dynamic		± 0.0025 mm/mm											
Life of ball bearings		3.6 x 10 ⁹ rotations											
Working temperature range		- 20 ... + 115 °C											
Storage temperature range		- 40 ... + 125 °C											
Permissible relative humidity ¹⁾		90 %											
Resistance													
to shocks ²⁾		100/10 g/ms											
to vibration ³⁾		20/10 ... 2000 g/Hz											
Protection to IEC 60529 ⁴⁾		IP 40											
EMC ⁵⁾													
Operating voltage range		7 ... 12 V											
Recommended supply voltage		8 V											
Max. operating current, no load		80 mA											
Available memory area													
within EEPROM 512		128 bytes											
within EEPROM 2048		1,792 bytes											
Interface signals													
Process data channel = SIN, REFSIN, COS, REFCOS	Analogue, differential												
Parameter channel = RS 485	Digital												

¹⁾ Condensation not permissible

²⁾ To DIN EN 60068-2-27

³⁾ To DIN EN 60068-2-6

⁴⁾ With mating connector inserted

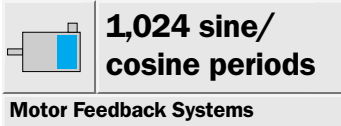
⁵⁾ To DIN EN 61000-6-2 and DIN 61000-6-3

The EMC according to the standards quoted is achieved when the motor feedback system is mounted in an electrically conductive housing, which is connected to the central earthing point of the motor controller via a cable screen. This is also where the GND (0 V) connection of the supply voltage is linked to earth. Users must perform their own tests when other screen designs are used.

Ordering information

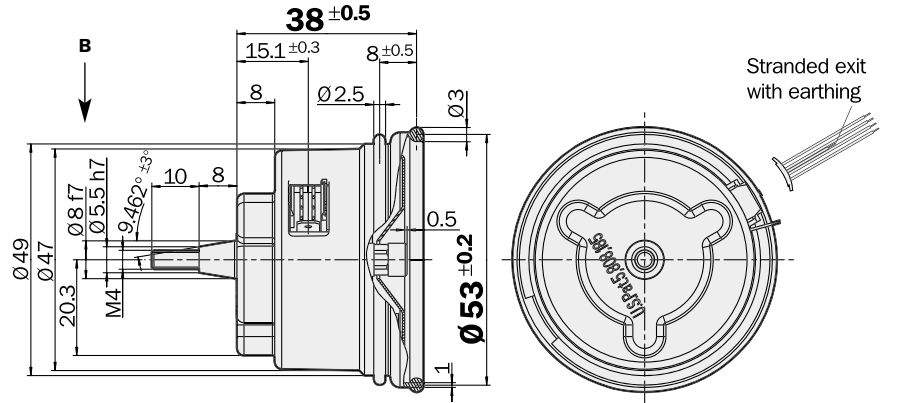
SRS/SRM 50; tapered shaft; resolver support

Type	Part no.	Description
SRS50-HGA0-K01	1 034 187	Single, 512 EEprom, , connector
SRS50-HGV0-K01	1 034 189	Single, 512 EEprom, stranded cable
SRS50-HGA0-K02	1 034 188	Single, 2048 EEprom, connector
SRS50-HGV0-K02	1 034 190	Single, 2048 EEprom, stranded cable
SRM50-HGA0-K01	1 034 124	Multi, 512 EEprom, , connector
SRM50-HGV0-K01	1 034 127	Multi, 512 EEprom, stranded cable
SRM50-HGA0-K02	1 034 125	Multi, 2048 EEprom, connector
SRM50-HGV0-K02	1 034 128	Multi, 2048 EEprom, stranded cable



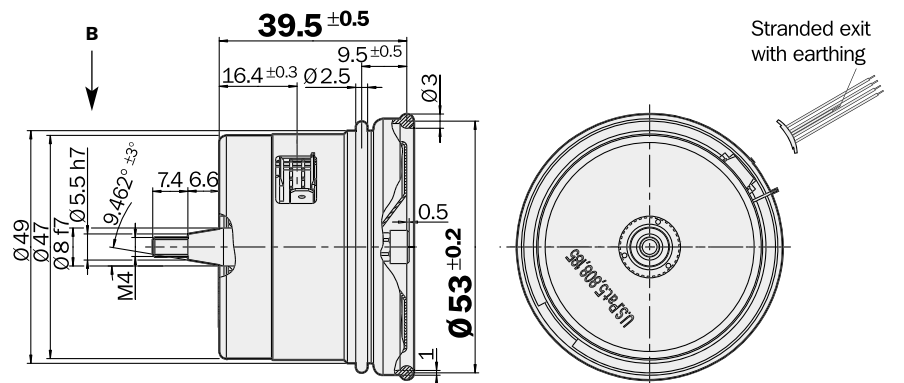
- 1,024 sine/cosine periods per revolution
- Absolute position with a resolution of 32,768 steps per revolution
- 4,096 revolutions can be measured (Multiturn)
- Programming of the positional value
- Electronic type label

Dimensional drawing SRS 50, rubber support Ø 50



General tolerances to DIN ISO 2768-mk

Dimensional drawing SRM 50, rubber support Ø 50

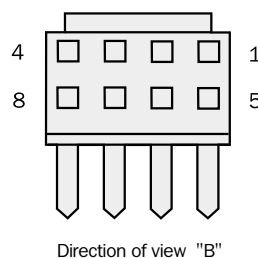


General tolerances to DIN ISO 2768-mk

PIN and wire allocation

PIN	Signal	Colour of Wires	Explanation
1	U _s	red	Supply voltage 7 ... 12 V
2	GND	blue	Ground connection
3	REFSIN	brown	Process data channel
4	REFCOS	black	Process data channel
5	Data +	grey	RS-485-parameter channel
6	Data -	green	RS-485-parameter channel
7	+ SIN	white	Process data channel
8	+ COS	pink	Process data channel

Caution: To ensure proper function, the screen connection strand (200 mm) MUST be connected. It is included in the supply.



Accessories

- Connection technology
- Fixing technology
- Programming tool

Technical Data		Tapered Shaft SRS/SRM 50	SRS	SRM									
Number of sine/cosine periods per revolution	1,024												
Dimensions	mm (see dimensional drawing)												
Mass	0.2 kg												
Inertial rotor moment	10 gcm ²												
Type of code for the absolute value	Binary												
Code sequence for clockwise shaft rotation, looking in direction "A" (see dimensional drawing)	Increasing												
Measurement step after generating arctan with 12 bit resolution	0.3 angular seconds												
Total number of steps	Single SRS 32,768												
	Multi SRM 134,217,728 = 32,768 x 4,096												
Error limits for the digital absolute value													
via RS 485	± 90 angular seconds												
Error limits for evaluating the "1,024" signals, integral non-linearity		± 45 angular seconds											
Non-linearity within a sine/cosine period													
differential non-linearity	± 7 angular seconds												
Output frequency for sine/cosine signals	0 ... 200 kHz												
Working speed up to which the absolute position can be reliably produced		6,000 min ⁻¹											
Max. operating speed	12,000 min ⁻¹												
Max. angular acceleration	0.2 x 10 ⁶ rad/s ²												
Operating torque	0.2 Ncm												
Starting torque	0.4 Ncm												
Permissible shaft movement													
static	radial/axial	± 0.5 mm/± 0.75 mm											
dynamic	radial/axial	± 0.1 mm/± 0.2 mm											
Angular motion, perpendicular to the rotational axis													
static		± 0.005 mm/mm											
dynamic		± 0.0025 mm/mm											
Life of ball bearings		3.6 x 10 ⁹ rotations											
Working temperature range		- 20 ... + 115 °C											
Storage temperature range		- 40 ... + 125 °C											
Permissible relative humidity ¹⁾		90 %											
Resistance													
to shocks ²⁾		100/10 g/ms											
to vibration ³⁾		20/10 ... 2000 g/Hz											
Protection to IEC 60529 ⁴⁾		IP 40											
EMC ⁵⁾													
Operating voltage range		7 ... 12 V											
Recommended supply voltage		8 V											
Max. operating current, no load		80 mA											
Available memory area													
within EEPROM 512		128 bytes											
within EEPROM 2048		1,792 bytes											
Interface signals													
Process data channel = SIN, REFSIN, COS, REFCOS	Analogue, differential												
Parameter channel = RS 485	Digital												

¹⁾ Condensation not permissible

²⁾ To DIN EN 60068-2-27

³⁾ To DIN EN 60068-2-6

⁴⁾ With mating connector inserted

⁵⁾ To DIN EN 61000-6-2 and DIN 61000-6-3

The EMC according to the standards quoted is achieved when the motor feedback system is mounted in an electrically conductive housing, which is connected to the central earthing point of the motor controller via a cable screen. This is also where the GND (0 V) connection of the supply voltage is linked to earth. Users must perform their own tests when other screen designs are used.

Ordering Information

SRS/SRM 50; tapered shaft; rubber support Ø 50 mm

Type	Part no.	Description
SRS50-HEA0-K01	1 034 176	Single, 512 EEprom, connector
SRS50-HEV0-K01	1 034 178	Single, 512 EEprom, stranded cable
SRS50-HEA0-K02	1 034 177	Single, 2048 EEprom, connector
SRS50-HEV0-K02	1 034 179	Single, 2048 EEprom, stranded cable
SRM50-HEA0-K01	1 034 111	Multi, 512 EEprom, connector
SRM50-HEV0-K01	1 034 114	Multi, 512 EEprom, stranded cable
SRM50-HEA0-K02	1 034 112	Multi, 2048 EEprom, connector
SRM50-HEV0-K02	1 034 115	Multi, 2048 EEprom, stranded cable

Motor Feedback Systems

- 12 SICK-STEGMANN

Technical Data		Tapered Shaft SRS/SRM 60	SRS	SRM									
Number of sine/cosine periods per revolution	1,024												
Dimensions	mm (see dimensional drawing)												
Mass	0.2 kg												
Inertial rotor moment	10 gcm ²												
Type of code for the absolute value	Binary												
Code sequence for clockwise shaft rotation, looking in direction "A" (see dimensional drawing)	Increasing												
Measurement step after generating arctan with 12 bit resolution	0.3 angular seconds												
Total number of steps	Single SRS 32,768												
	Multi SRM 134,217,728 = 32,768 x 4,096												
Error limits for the digital absolute value													
via RS 485	± 90 angular seconds												
Error limits for evaluating the "1,024" signals, integral non-linearity		± 45 angular seconds											
Non-linearity within a sine/cosine period													
differential non-linearity	± 7 angular seconds												
Output frequency for sine/cosine signals	0 ... 200 kHz												
Working speed up to which the absolute position can be reliably produced		6,000 min ⁻¹											
Max. operating speed	12,000 min ⁻¹												
Max. angular acceleration	0.2 x 10 ⁶ rad/s ²												
Operating torque	0.2 Ncm												
Starting torque	0.4 Ncm												
Permissible shaft movement													
static	radial/axial	± 0.5 mm/± 0.75 mm											
dynamic	radial/axial	± 0.1 mm/± 0.2 mm											
Angular motion, perpendicular to the rotational axis													
static		± 0.005 mm/mm											
dynamic		± 0.0025 mm/mm											
Life of ball bearings		3.6 x 10 ⁹ rotations											
Working temperature range		- 20 ... + 115 °C											
Storage temperature range		- 40 ... + 125 °C											
Permissible relative humidity ¹⁾		90 %											
Resistance													
to shocks ²⁾		100/10 g/ms											
to vibration ³⁾		20/10 ... 2000 g/Hz											
Protection to IEC 60529 ⁴⁾		IP 40											
EMC ⁵⁾													
Operating voltage range		7 ... 12 V											
Recommended supply voltage		8 V											
Max. operating current, no load		80 mA											
Available memory area													
within EEPROM 512		128 bytes											
within EEPROM 2048		1,792 bytes											
Interface signals													
Process data channel = SIN, REFSIN, COS, REFCOS	Analogue, differential												
Parameter channel = RS 485	Digital												

¹⁾ Condensation not permissible

²⁾ To DIN EN 60068-2-27

³⁾ To DIN EN 60068-2-6

⁴⁾ With mating connector inserted

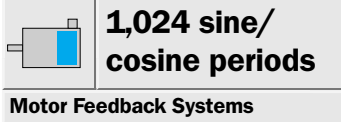
⁵⁾ To DIN EN 61000-6-2 and DIN 61000-6-3

The EMC according to the standards quoted is achieved when the motor feedback system is mounted in an electrically conductive housing, which is connected to the central earthing point of the motor controller via a cable screen. This is also where the GND (0 V) connection of the supply voltage is linked to earth. Users must perform their own tests when other screen designs are used.

Ordering information

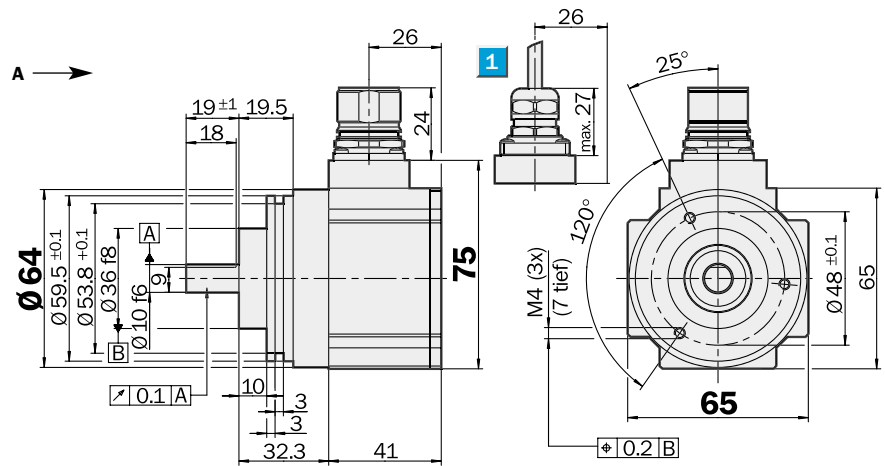
SRS/SRM 60; tapered shaft; rubber support Ø 60 mm

Type	Part no.	Description
SRS60-HEA0-K01	1 034 217	Single, 512 EEprom, connector
SRS60-HEV0-K01	1 034 220	Single, 512 EEprom, stranded cable
SRS60-HEA0-K02	1 034 218	Single, 2048 EEprom, connector
SRS60-HEV0-K02	1 034 221	Single, 2048 EEprom, stranded cable
SRM60-HEA0-K01	1 034 157	Multi, 512 EEprom, connector
SRM60-HEV0-K01	1 034 160	Multi, 512 EEprom, stranded cable
SRM60-HEA0-K02	1 034 158	Multi, 2048 EEprom, connector
SRM60-HEV0-K02	1 034 161	Multi, 2048 EEprom, stranded cable



- 1,024 sine/cosine periods per revolution
- Absolute position with a resolution of 32,768 steps per revolution
- 4,096 revolutions can be measured (Multiturn)
- Programming of the positional value
- Electronic type label

Dimensional drawing SRS 50 standalone, rectangular housing, face mount flange

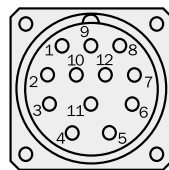


1 R = min. bending radius 40 mm

General tolerances to DIN ISO 2768-mk

PIN and wire allocation

PIN	Signal	Colour of Wires	Explanation
1	REFCOS	black	Process data channel
2	Data +	grey	RS-485-parameter channel
3	N. C.	–	N. C.
4	N. C.	–	N. C.
5	SIN	white	Process data channel
6	REFSIN	brown	Process data channel
7	Data –	green	RS-485-parameter channel
8	COS	pink	Process data channel
9	N. C.	–	N. C.
10	GND	blue	Ground connection
11	N. C.	–	N. C.
12	U _s	red	7 ... 12 V Supply voltage



View of the plug-in face

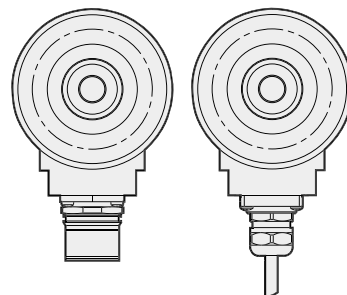
Screen connection on connector housing

N. C. = Not connected

Type of connection

Connector radial

Cable radial



Accessories

- Connection technology
- Fixing technology
- Programming tool



Technical Data		Standalone, Face Mount Flange SRS/SRM 50									
		SRS	SRM								
Number of sine/cosine periods per revolution	1,024										
Dimensions	mm (see dimensional drawing)										
Mass	0.550 kg										
Inertial rotor moment	25 gcm ²										
Type of code for the absolute value	Binary										
Code sequence for clockwise shaft rotation, looking in direction "A" (see dimensional drawing)	Increasing										
Measurement step after generating arctan with 12 bit resolution	0.3 angular seconds										
Total number of steps	Single SRS 32,768										
	Multi SRM 134,217,728 = 32,768 x 4,096										
Error limits for the digital absolute value											
via RS 485	± 90 angular seconds										
Error limits for evaluating the "1,024" signals,											
integral non-linearity	± 45 angular seconds										
Non-linearity within a sine/cosine period											
differential non-linearity	± 7 angular seconds										
Output frequency for sine/cosine signals	0 ... 200 kHz										
Working speed up to which the absolute position can be reliably produced											
Max. operating speed	6,000 min ⁻¹										
Max. angular acceleration	0.2 x 10 ⁶ rad/s ²										
Operating torque with shaft sealing ring	1 Ncm										
Starting torque with shaft sealing ring	1.5 Ncm										
Load capacity of shaft	radial/axial 40 N/20 N										
Life of ball bearings	3.6 x 10 ⁹ rotations										
Working temperature range	- 20 ... + 85 °C										
Storage temperature range	- 30 ... + 90 °C										
Permissible relative humidity ¹⁾	90 %										
Resistance											
to shocks ²⁾	30/11 g/ms										
to vibration ³⁾	20/10 ... 2000 g/Hz										
Protection to IEC 60529 ⁴⁾	IP 65										
EMC ⁵⁾											
Operating voltage range	7 ... 12 V										
Recommended supply voltage	8 V										
Max. operating current, no load	80 mA										
Available memory area											
within EEPROM 512	128 bytes										
within EEPROM 2048	1,792 bytes										
Interface signals											
Process data channel = SIN, REFSIN, COS, REFCOS	Analogue, differential										
Parameter channel = RS 485	Digital										

¹⁾ Condensation not permissible

²⁾ To DIN EN 60068-2-27

³⁾ To DIN EN 60068-2-6

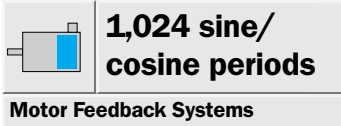
⁴⁾ With mating connector inserted

⁵⁾ To DIN EN 61000-6-2 and DIN 61000-6-3

Ordering information

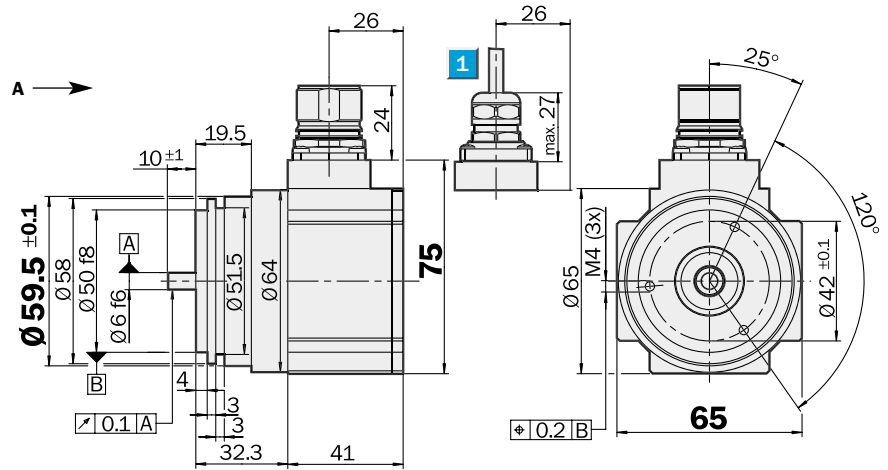
SRS/SRM 50 standalone; solid shaft Ø 10 mm; clamping flange

Type	Part no.	Description
SRS50-HWA0-K01	1 034 192	Single, 512 EEprom, connector
SRS50-HWV0-K01	1 034 194	Single, 512 EEprom, cable 1,5 m
SRS50-HWA0-K02	1 034 193	Single, 2048 EEprom, connector
SRS50-HWV0-K02	1 034 195	Single, 2048 EEprom, cable 1,5 m
SRM50-HWA0-K01	1 034 130	Multi, 512 EEprom, connector
SRM50-HWV0-K01	1 034 133	Multi, 512 EEprom, cable 1,5 m
SRM50-HWA0-K02	1 034 131	Multi, 2048 EEprom, connector
SRM50-HWV0-K02	1 034 134	Multi, 2048 EEprom, cable 1,5 m



- 1,024 sine/cosine periods per revolution
- Absolute position with a resolution of 32,768 steps per revolution
- 4,096 revolutions can be measured (Multiturn)
- Programming of the positional value
- Electronic type label

Dimensional drawing SRS 50 standalone, rectangular housing, servo flange

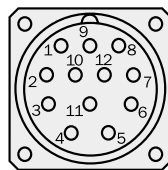


1 R = min. bending radius 40 mm

General tolerances to DIN ISO 2768-mk

PIN and wire allocation

PIN	Signal	Colour of Wires	Explanation
1	REFCOS	black	Process data channel
2	Data +	grey	RS-485-parameter channel
3	N. C.	–	N. C.
4	N. C.	–	N. C.
5	SIN	white	Process data channel
6	REFSIN	brown	Process data channel
7	Data –	green	RS-485-parameter channel
8	COS	pink	Process data channel
9	N. C.	–	N. C.
10	GND	blue	Ground connection
11	N. C.	–	N. C.
12	U _s	red	7 ... 12 V Supply voltage



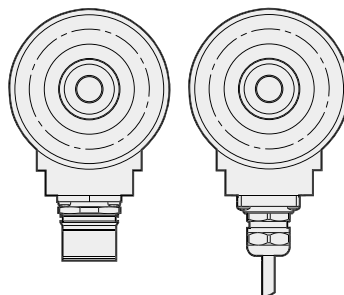
View of the plug-in face

Screen connection on connector housing

N. C. = Not connected

Type of connection

Connector radial Cable radial



Accessories

Connection technology
Fixing technology
Programming tool



Technical Data		Standalone, Servo Flange SRS/SRM 50	SRS	SRM									
Number of sine/cosine periods per revolution	1,024												
Dimensions	mm (see dimensional drawing)												
Mass	0.550 kg												
Inertial rotor moment	25 gcm ²												
Type of code for the absolute value	Binary												
Code sequence for clockwise shaft rotation, looking in direction "A" (see dimensional drawing)	Increasing												
Measurement step after generating arctan with 12 bit resolution	0.3 angular seconds												
Total number of steps	Single SRS 32,768												
	Multi SRM 134,217,728 = 32,768 x 4,096												
Error limits for the digital absolute value													
via RS 485	± 90 angular seconds												
Error limits for evaluating the "1,024" signals, integral non-linearity	± 45 angular seconds												
Non-linearity within a sine/cosine period													
differential non-linearity	± 7 angular seconds												
Output frequency for sine/cosine signals	0 ... 200 kHz												
Working speed up to which the absolute position can be reliably produced	6,000 min ⁻¹												
Max. operating speed	6,000 min ⁻¹												
Max. angular acceleration	0.2 x 10 ⁶ rad/s ²												
Operating torque with shaft sealing ring	1 Ncm												
Starting torque with shaft sealing ring	1.5 Ncm												
Load capacity of shaft	radial/axial 40 N/20 N												
Life of ball bearings	3.6 x 10 ⁹ rotations												
Working temperature range	- 20 ... + 85 °C												
Storage temperature range	- 30 ... + 90 °C												
Permissible relative humidity ¹⁾	90 %												
Resistance													
to shocks ²⁾	30/11 g/ms												
to vibration ³⁾	20/10 ... 2000 g/Hz												
Protection to IEC 60529 ⁴⁾	IP 65												
EMC ⁵⁾													
Operating voltage range	7 ... 12 V												
Recommended supply voltage	8 V												
Max. operating current, no load	80 mA												
Available memory area													
within EEPROM 512	128 bytes												
within EEPROM 2048	1,792 bytes												
Interface signals													
Process data channel = SIN, REFSIN, COS, REFCOS	Analogue, differential												
Parameter channel = RS 485	Digital												

¹⁾ Condensation not permissible

²⁾ To DIN EN 60068-2-27

³⁾ To DIN EN 60068-2-6

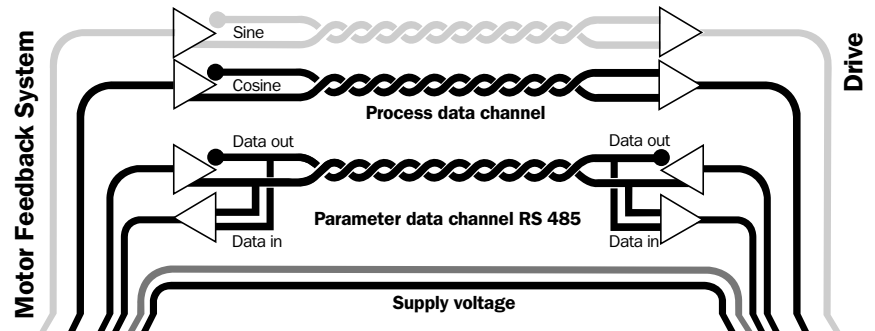
⁴⁾ With mating connector inserted

⁵⁾ To DIN EN 61000-6-2 and DIN 61000-6-3

Ordering information		
SRS/SRM 50 standalone; solid shaft Ø 6 mm; servo flange		
Type	Part no.	Description
SRS50-HXA0-K01	1 034 197	Single, 512 EEprom, connector
SRS50-HXV0-K01	1 034 199	Single, 512 EEprom, cable 1,5 m
SRS50-HXA0-K02	1 034 198	Single, 2048 EEprom, connector
SRS50-HXV0-K02	1 034 200	Single, 2048 EEprom, cable 1,5 m
SRM50-HXA0-K01	1 034 136	Multi, 512 EEprom, connector
SRM50-HXV0-K01	1 034 138	Multi, 512 EEprom, cable 1,5 m
SRM50-HXA0-K02	1 034 137	Multi, 2048 EEprom, connector
SRM50-HXV0-K02	1 034 139	Multi, 2048 EEprom, cable 1,5 m

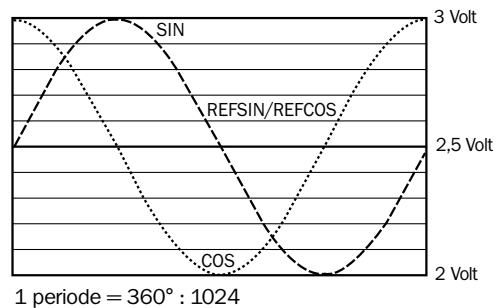
Electrical interface

- Safe data transmission
- High information content
- Electronic type label
- Only 8 leads
- Bus-enabled parameter channel
- Process data channel in real time



Signal specification of the process data channel

Signal diagram for clockwise rotation of the shaft, looking in direction "A"



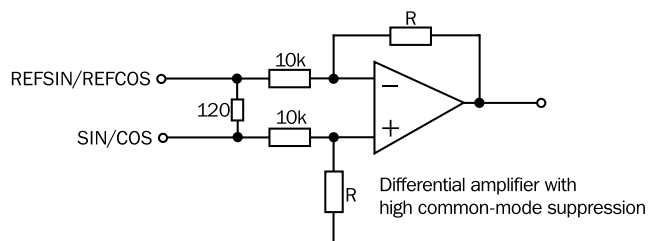
Access to the process data used for speed control, i.e. to the sine and cosine signals, is practically always "online". When the supply voltage is applied, the speed controller has access to this information at any time.

Sophisticated technology guarantees stable amplitudes of the analogue signals across all specified environmental conditions, with a maximum variation of only 20%.

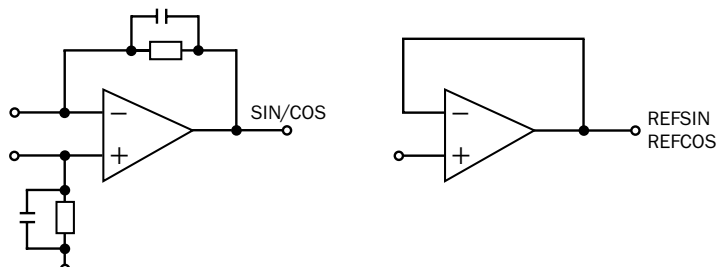
Characteristics applicable to all permissible environmental conditions signal

Signal	Values/Units
Signal peak, peak V_{SS} of SIN, COS	0.9 ... 1.1 V
Signal offset REFSIN, REFCOS	2.2 ... 2.8 V

Recommended receiver circuit for sine and cosine signals



The output circuit of the process data channel within the SinCos encoder





Type-specific settings	SRS	SRM
Type ID (command 52h)	22h	27h
Free EEPROM [bytes]	128/1,792	128/1,792
Address	40h	40h
Mode_485	E4h	E4h
Codes 0 ... 3	55h	55h
Counter	0	0

Overview of commands supported			SRS	SRM
Command byte	Function	Code 0 ¹⁾	Comments	Comments
42h	Read position			
43h	Set position	•		
44h	Read analogue value		Channel number 48h	Channel number 48h
			Temperature [°C]	Temperature [°C]
46h	Read counter			
47h	Increase counter			
49h	Reset counter	•		
4Ah	Read data			
4Bh	Save data			
4Ch	Determine status of a data field			
4Dh	Create data field			
4Eh	Determine available memory area			
4Fh	Change access code			
50h	Read encoder status			
52h	Read out name plate		Encoder type = 22h	Encoder type = 27h
53h	Encoder reset			
55h	Allocate encoder address	•		
56h	Read serial number and program version			
57h	Configure serial interface	•		

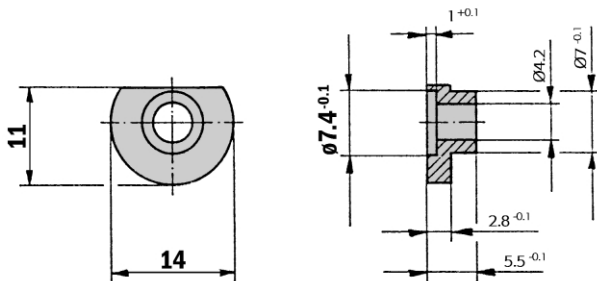
¹⁾ The commands thus labelled include the parameter "Code 0". Code 0 is a byte inserted into the protocol, for additional safeguarding of vital system parameters against accidental overwriting. When shipped, "Code 0" = 55h

Overview of status messages				
Error type	Status code	Description	SRS	SRM
	00h	The encoder has recognised no error	•	•
Initialisation	01h	Faulty compensating data	•	•
	02h	Faulty internal angular offset	•	•
	03h	Data field partitioning table damaged	•	•
	04h	Analogue limit values not available	•	•
	05h	Internal I ² C bus not operational	•	•
	06h	Internal checksum error	•	•
Protocol	07h	Encoder reset occurred as a result of program monitoring	•	•
	09h	Parity error	•	•
	0Ah	Checksum of the data transmitted is incorrect	•	•
	0Bh	Unknown command code	•	•
	0Ch	Number of data transmitted is incorrect	•	•
	0Dh	Command argument transmitted is not allowed	•	•
Data	0Eh	The selected data field must not be written to	•	•
	0Fh	Incorrect access code	•	•
	10h	Size of data field stated cannot be changed	•	•
	11h	Size of data field stated cannot be changed	•	•
	12h	Access to non-existent data field	•	•
Position	01h	Analogue signals outside specification	•	•
	1Fh	Speed too high, no position formation possible	•	•
	20h	Singleturn position unreliable	•	•
	21h	Positional error Multiturn		•
	22h	Positional error Multiturn		•
	23h	Positional error Multiturn		•
Other	1Ch	Monitoring the value of the analogue signals (process data)		
	1Dh	Transmitter current critical (dirt, transmitter breakage)	•	•
	1Eh	Encoder temperature critical	•	•
	08h	Counter overflow	•	•

Dimensional drawings and ordering information

Servo clamp small, set (contents 3 off) for servo flanges

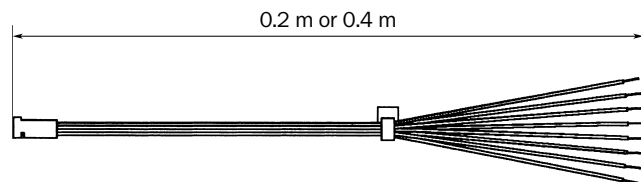
Type	Part no.
BEF-WK-SF	2 029 166



General tolerances to DIN ISO 2768-mk

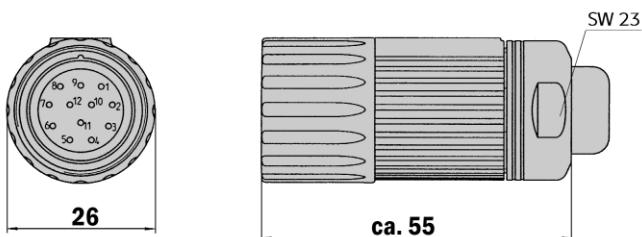
Stranded cable/connector, straight, 8 wires, 8 x 0,24 mm²

Type	Part no.	Contacts	Wire length
DOL-OB08-GOM2XB1	2 031 081	8	0.2 m
DOL-OB08-GOM4XB1	2 031 083	8	0.4 m



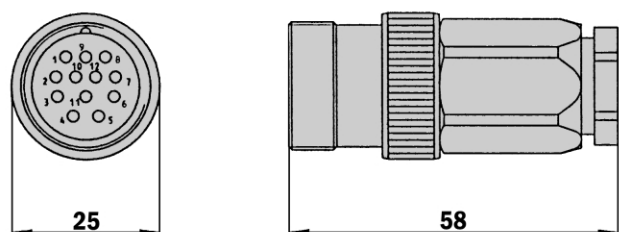
Connector M23 female, 12 pin, straight

Type	Part no.	Contacts
DOS-2312-G	6 027 538	12



Connector M23 male, 12 pin, straight, screened

Type	Part no.	Contacts
STE-2312-G	6 027 537	12



Dimensional drawings and ordering information
Cable connector M23, 12 pin, straight, cable 8 core, HIPERFACE[®], screened

Type	Part no.	Contacts	Cable length
DOL-2308-G1M5JB2	2 031 069	12	1.5 m
DOL-2308-G03M5JB2	2 031 070	12	3.0 m
DOL-2308-G05M5JB2	2 031 071	12	5.0 m
DOL-2308-G10M5JB2	2 031 072	12	10.0 m
DOL-2308-G15M5JB2	2 031 073	12	15.0 m

HIPERFACE[®] cable, 8 wires, supplied by the metre 4 x 2 x 0,15 mm²

Type	Part no.	Cores
LTG-2708-MW	6 028 361	8

Programming tool for HIPERFACE[®] devices

Type	Part no.	Motor Feedback System
PGT-03-S	1 034 252	SRS/SRM 50 standalone

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